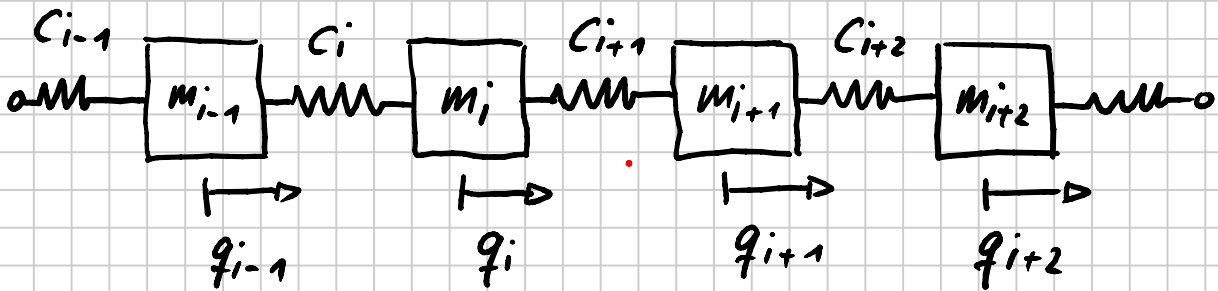


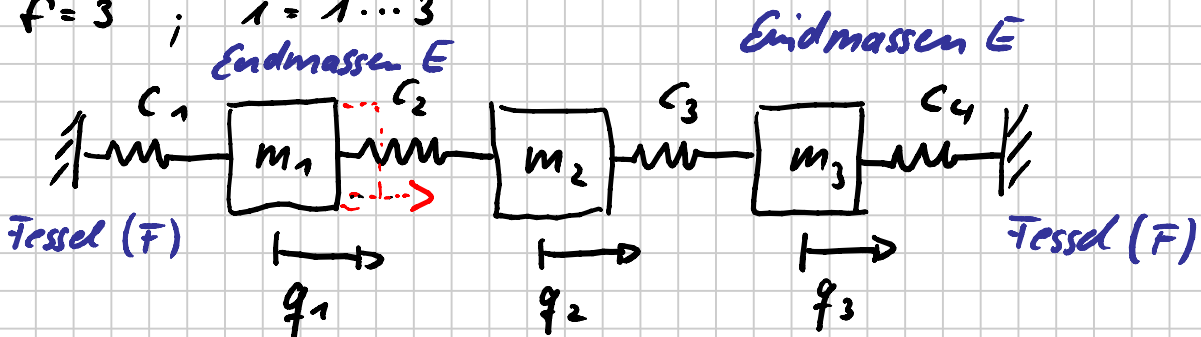
# 7. Modalanalyse, Modellbildung 2

Bsp. 3 elastische Ketten, lineare Schwingerketten  $f=n, n > 1$



Dgl.: 
$$m_i \ddot{q}_i = -C_i (q_i - q_{i-1}) + C_{i+1} (q_{i+1} - q_i)$$

Bsp.:  $f=3; i=1 \dots 3$



$i=1$

$$m_1 \ddot{q}_1 = -C_1 (q_1 - 0) + C_2 (q_2 - q_1)$$

$$m_1 \ddot{q}_1 + (C_1 + C_2) q_1 - C_2 q_2 = 0 \quad (1)$$

$i=2$

$$m_2 \ddot{q}_2 = -C_2 (q_2 - q_1) + C_3 (q_3 - q_2)$$

$$m_2 \ddot{q}_2 + (C_2 + C_3) q_2 - C_2 q_1 - C_3 q_3 = 0 \quad (2)$$

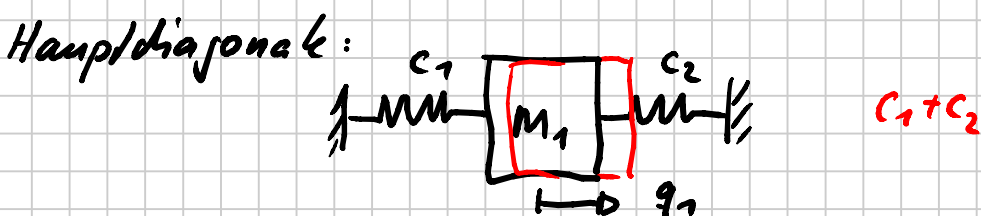
$i=3$

$$m_3 \ddot{q}_3 = -C_3 (q_3 - q_2) + C_4 (0 - q_3)$$

$$m_3 \ddot{q}_3 + (C_3 + C_4) q_3 - C_3 q_2 = 0 \quad (3)$$

$$\begin{bmatrix} m_1 & 0 & 0 \\ 0 & m_2 & 0 \\ 0 & 0 & m_3 \end{bmatrix} \cdot \begin{bmatrix} \ddot{q}_1 \\ \ddot{q}_2 \\ \ddot{q}_3 \end{bmatrix} + \begin{bmatrix} C_1 + C_2 & -C_2 & 0 \\ -C_2 & C_2 + C_3 & -C_3 \\ 0 & -C_3 & C_3 + C_4 \end{bmatrix} \cdot \begin{bmatrix} q_1 \\ q_2 \\ q_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$M \cdot \ddot{\mathbf{q}} + C \cdot \mathbf{q} = \mathbf{0}$

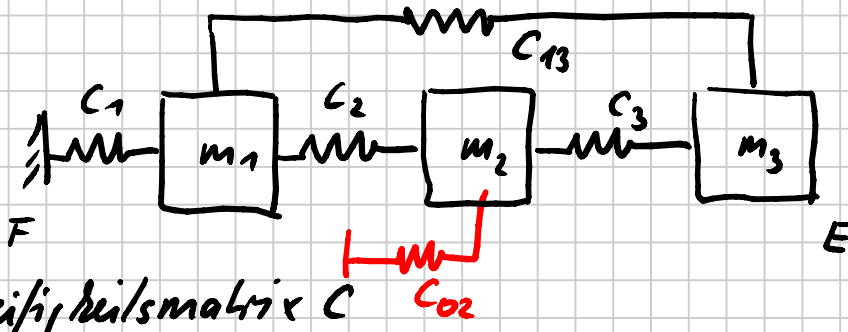


Kopplung



$-c_2$

Bsp.  $f=3$



Steifigkeitsmatrix C

$$C = \begin{bmatrix} c_1 + c_2 & -c_2 & c_{13} \\ -c_2 & c_2 + c_3 + c_{02} & -c_3 \\ -c_{13} & -c_3 & c_3 \end{bmatrix}$$



$$M \ddot{\bar{q}} + K \dot{\bar{q}} + C \bar{q} = \bar{f}_e \quad f > 1 \quad \bar{f}_e = \begin{bmatrix} F_1(t) \\ F_2(t) \\ \vdots \\ F_n(t) \end{bmatrix}$$

$$m \ddot{q} + k \dot{q} + c q = F(t) \quad f=1$$