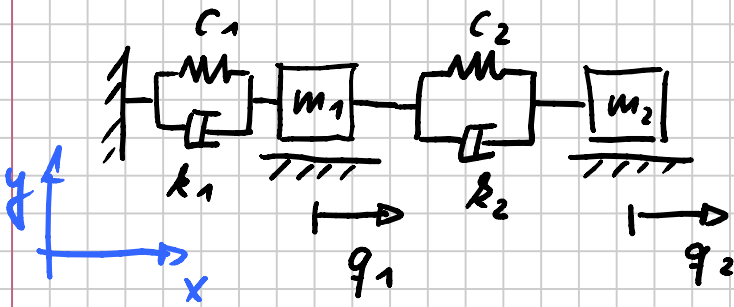


# 6. Modalanalyse, Modellbildung, $f > 1$

Bsp. 1



unabhängige Koordinaten

$$q_1, q_2 \Rightarrow f = 2$$

Bewegungsgleichung

$$q_1: m_1 \ddot{q}_1 = k_2(\dot{q}_2 - \dot{q}_1) - k_1 \dot{q}_1 + c_2(q_2 - q_1) - c_1 \dot{q}_1 \quad (1)$$

$$q_2: m_2 \ddot{q}_2 = -k_2(\dot{q}_2 - \dot{q}_1) - c_2(q_2 - q_1) \quad (2)$$

$$(1) \quad m_1 \ddot{q}_1 + (k_1 + k_2) \dot{q}_1 - k_2 \dot{q}_2 + (c_1 + c_2) q_1 - c_2 q_2 = 0$$

$$(2) \quad m_2 \ddot{q}_2 + k_2 \dot{q}_2 - k_2 \dot{q}_1 + c_2 q_2 - c_2 q_1 = 0$$

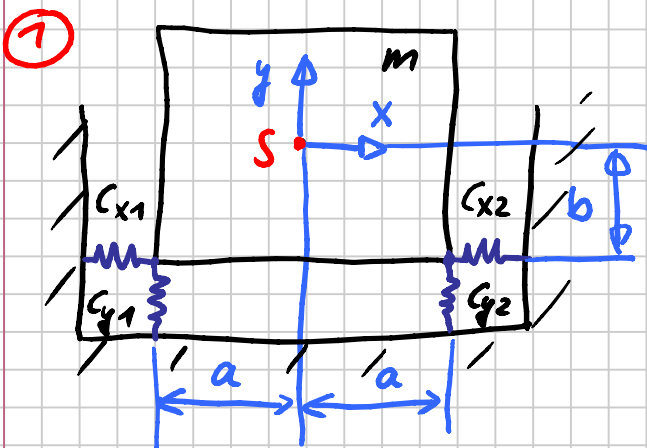
$$\begin{bmatrix} m_1 & 0 \\ 0 & m_2 \end{bmatrix} \cdot \begin{bmatrix} \ddot{q}_1 \\ \ddot{q}_2 \end{bmatrix} + \begin{bmatrix} k_1+k_2 & -k_2 \\ -k_2 & k_2 \end{bmatrix} \cdot \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \end{bmatrix} + \begin{bmatrix} c_1+c_2 & -c_2 \\ -c_2 & c_2 \end{bmatrix} \cdot \begin{bmatrix} q_1 \\ q_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$M \cdot \ddot{\bar{q}} + K \cdot \dot{\bar{q}} + C \cdot \bar{q} = \bar{0}$$

$$M \ddot{\bar{q}} + K \dot{\bar{q}} + C \bar{q} = \bar{0} \quad f > 1$$

$$m \ddot{q} + k \dot{q} + c q = 0 \quad f = 1$$

Bsp. 2. Blockfundament



$$\bar{x}: m \ddot{x} = -(c_{x1} + c_{x2})x - (c_{x1} + c_{x2})\Delta x$$

$$\Delta x = a(1 - \cos \varphi) + b \sin \varphi$$

Linearisierung  $\cos \varphi \approx 1, \sin \varphi \approx \varphi$

$$\Delta x = b \cdot \varphi$$

$$m \ddot{x} = -(c_{x1} + c_{x2})x - (c_{x1} + c_{x2})b \cdot \varphi \quad (1)$$

$$\bar{y}: m \ddot{y} = -(c_{y1} + c_{y2})y - (c_{y2} - c_{y1})\Delta y$$

$$\Delta y = a \sin \varphi + b(1 - \cos \varphi)$$

$$\Delta y = a \varphi$$

$$m \ddot{y} = -(c_{y1} + c_{y2})y - (c_{y2} - c_{y1})a \varphi \quad (2)$$



$$\bar{c}_2: \bar{f}_s \ddot{\varphi} = - (c_{x1} + c_{x2}) b x - (c_{y1} - c_{y2}) a y - (c_{x1} + c_{x2}) b^2 \varphi - (c_{y1} + c_{y2}) a^2 \varphi \quad (3)$$

unabh. hängige Koordinaten:

$$x, y, \varphi \quad f = 3 !$$

$$\begin{bmatrix} m & 0 & 0 \\ 0 & m & 0 \\ 0 & 0 & \bar{f}_s \end{bmatrix} \cdot \begin{bmatrix} \ddot{x} \\ \ddot{y} \\ \ddot{\varphi} \end{bmatrix} + \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ \varphi \end{bmatrix} = \bar{0}$$

$$M \cdot \ddot{\bar{q}} + C \cdot \bar{q} = \bar{0}$$

$$c_{11} = c_{x1} + c_{x2}$$

$$c_{12} = 0$$

$$c_{13} = (c_{x1} + c_{x2}) b$$

$$c_{22} = c_{y1} + c_{y2}$$

$$c_{21} = 0$$

$$c_{23} = (c_{y1} - c_{y2}) \cdot a = c_{32}$$

$$c_{33} = (c_{x1} + c_{x2}) b^2 + (c_{y1} + c_{y2}) a^2$$

$$c_{31} = (c_{x1} + c_{x2}) b$$